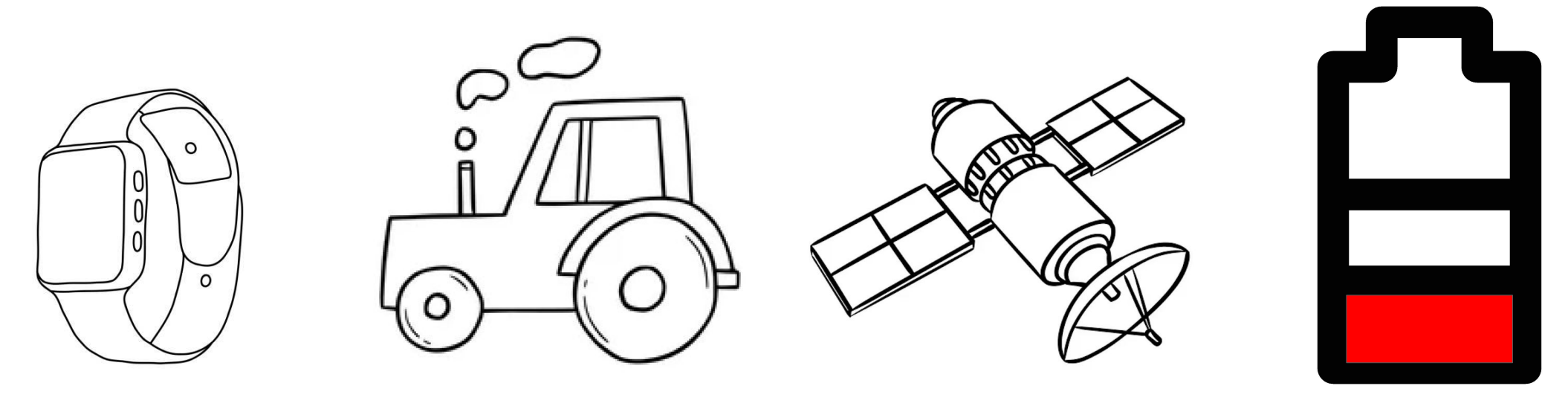
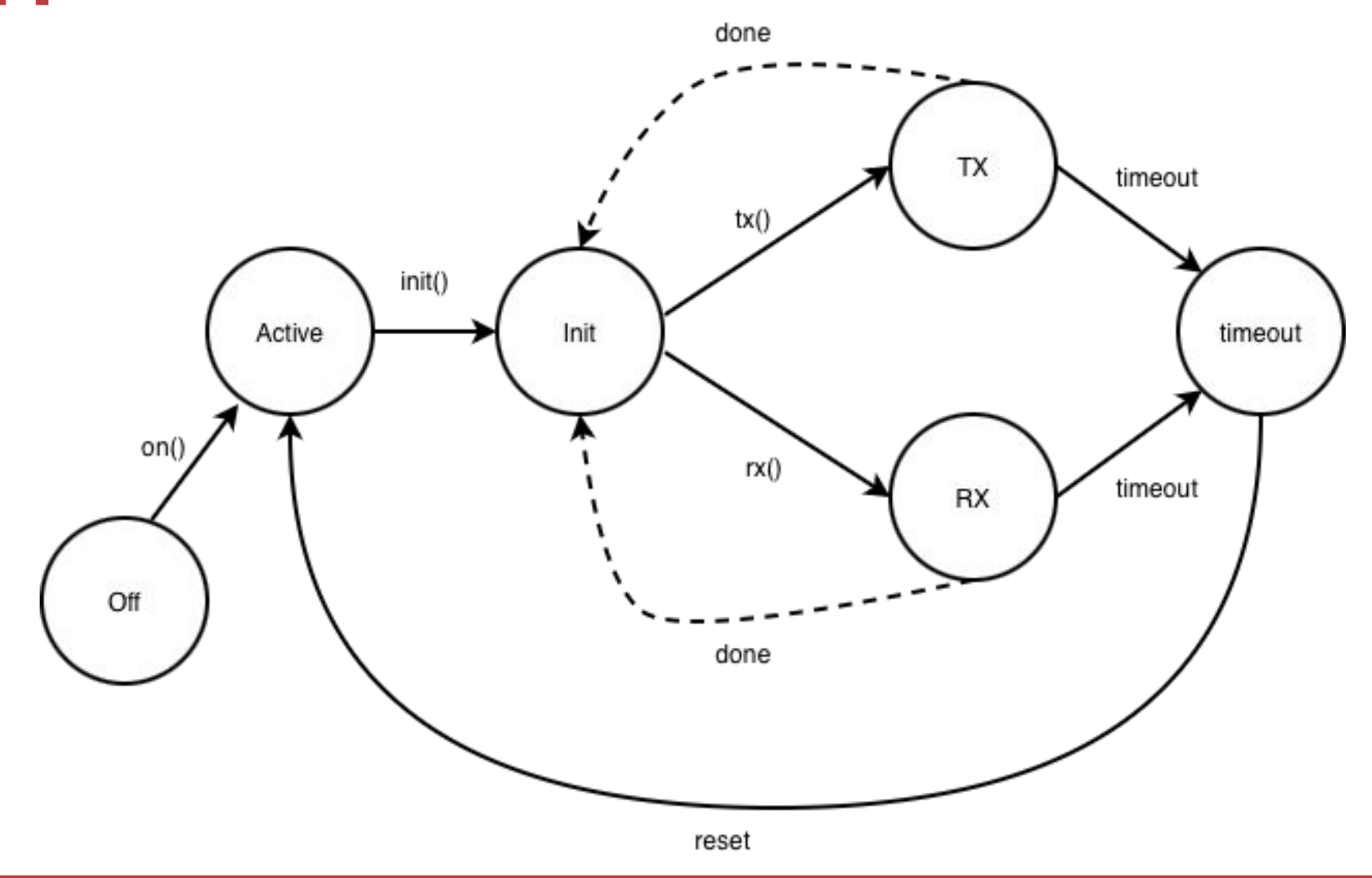


## Background + Motivation



Embedded systems have limited energy budget - used in diverse applications



Complex state difficult to reason about

Two prior approaches: measurements, static analysis

Measurement	Static Analysis
Accurate but difficult to do	Easy but relies on assumptions

## Our Approach

Combine automatic amortized resource analysis with **typestate** for accurate, expressive peripheral reasoning

## Categories of energy costs

1. Main board execution
2. Peripheral operations
3. Active **background** peripherals

some\_other\_func() represents generic computation

Code	I2C State
transition(i2C, Tx);	? → Tx
i2C.transmit();	Tx
some_other_func();	Tx
i2C.stop();	Tx → Stop

## Cost Reporting

- C - fixed expression cost
- C(p : st) - peripheral p in st
- C(p : (st, st')) - peripheral p transitioning st -> st'

Symbolic costs for hardware agnostic reasoning

## Cost Analysis Example

```
fn log_data(temp) -> u64 {
  transition(temp, Mes);
  let res = temp.measure();
  let t = 0;
  if(res <= 65) {
    t = 1;
  }
  transition(temp, Idle);
  return t;
}
```

C(temp: (???, Measure))  
 $C_m + C(\text{temp: Measure})$   
 $C_v + C(\text{temp: Measure})$   
 $\max(C_v, 0) + C(\text{temp: Measure})$   
 $C(\text{temp: (Measure, Idle)})$

Total Cost:  $C_1 = C(\text{temp: (???, Measure)}) + 2C_v + C_m + 3C(\text{temp: Measure}) + C(\text{temp: (Measure, Idle)})$

## State Inference Motivation

Initial state depends on previous behavior

Annotations can be error-prone  
 Polymorphism can lead to conservatism

```
fn main() {
  transition(temp, Idle); C(temp: (Off, Idle))
  let t = log_data(temp); C1[?? = Idle]
}
```

```
fn main() {
  C(temp: (Off, Idle)) transition(temp, Idle);
  C(temp: (Idle, Measure)) transition(temp, Measure);
  Cm + C(temp: Measure) let m = temp.measure();
  C1[?? = Measure] let t = log_data(temp);
}
```

## State Inference Example

New state variable per transition - similar to type variables

```
fn main() {
  temp = [a0]
  transition(temp, Idle); temp = [a1 :: a0]
  Φ = a0 ≤ a1 ∧ a1 = Idle
  let t = log_data(temp); solve(Φ ∧ a1 ≤ Measure)
}
```

Constraints combined at function calls

State variable stack tracks peripheral history

## Conclusion

Type system for reasoning about energy consumption with stateful peripherals.  
 Next steps: support async operations, finish implementation